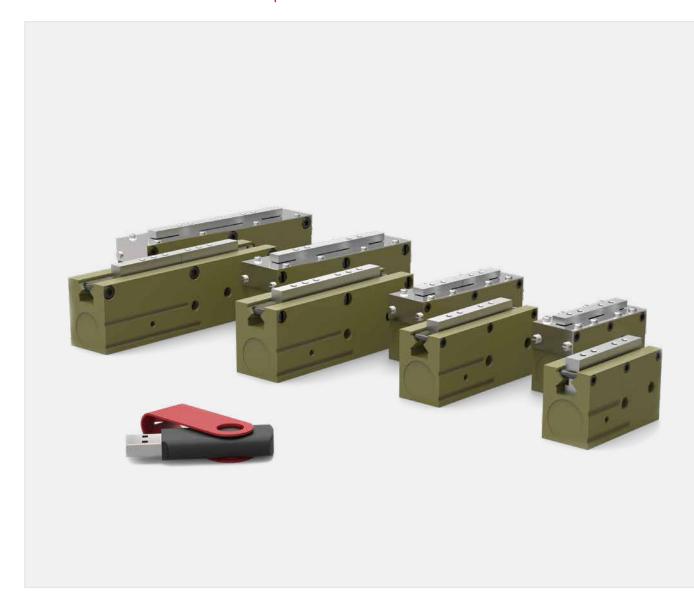


Service Manual

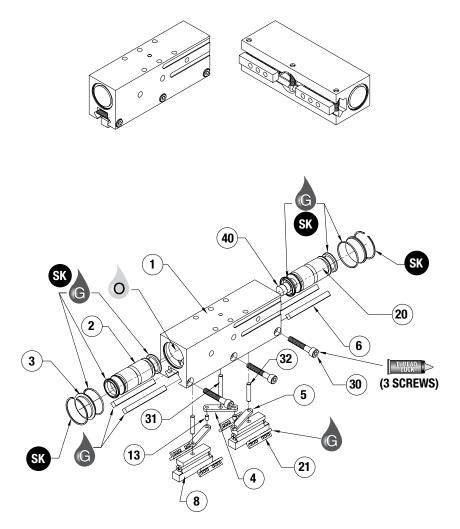
ROBOHAND | RPL/RPLC Series



WARNING: This is a controlled document. It is your responsibility to deliver this information to the end user of the Destaco Robohand product. Failure to deliver this could result in your liability for injury to the user or damage to the machine. For copies of this manual, call your Customer Service Representative at 1.248.836.6700

RPL SERIES

Parallel Grippers | Maintenance and Assembly Procedure



| Item | Qty | Name |
|------|-----|-----------------------|
| 01 | 1 | Body |
| 02 | 1 | Piston |
| 03 | 2 | Cap |
| 04 | 1 | Equalizer |
| 05 | 2 | Link |
| 06 | 4 | Way |
| 80 | 2 | Jaw |
| 13 | 2 | Pin |
| 20 | 1 | Piston W/Magnet Slot |
| 21 | 4 | S'assy,Cage & Rollers |
| 30 | 3 | SHCS |
| 31 | 1 | Dowel Pin |
| 32 | 2 | Dowel Pin |
| 40 | 2 | Magnet |
| | | |

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install seals.
- 2) Press dowel pin into center of body.
- 3) Place links and equalizers into body.
- 4) Press dowel pins into jaws.
 5) Place jaws through links and into pistons.
- Install cages on jaws.
 Place ways behind cages with flat facing out and install screws.
 Adjust preload.

- **Preload Adjustment Procedure**1) Tighten center screw (#30) so that fingers bind slightly.
- 2) Tighten outer screws in the same fashion.
- 3) Cycle the gripper.
 4) Re-adjust screws so that when you push the cage, the finger moves freely. (the finger movement should not feel gritty.)

Non-Synchronous Procedure

- 1) Remove preload screws (#30) and ways.
- 2) Remove cages, jaws and dowel pins.
- 3) Remove equalizer, links, and roller
- 4) Re-assemble jaws and dowel pins into pistons.

 5) Re-install cages on jaws.
- 6) Place ways behind cages with flat facing out and install preload screws.
- 7) Adjust preload.













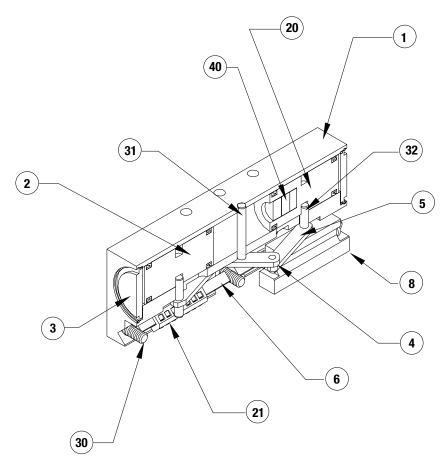






RPL SERIES

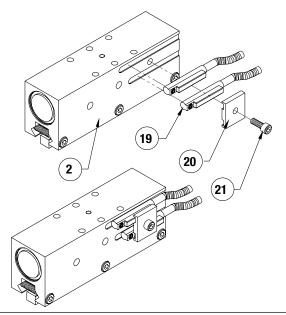
Parallel Grippers | Maintenance and Assembly Procedure



| 01 1 Body 02 1 Piston 03 2 Cap 04 1 Equalizer | |
|---|----|
| 02 1 Piston 03 2 Cap | |
| 03 2 Cap | |
| | |
| 04 1 Equalizer | |
| ut i Lyualizei | |
| 05 2 Link | |
| 06 4 Way | |
| 08 2 Jaw | |
| 13 2 Bearing,Roller | |
| 20 1 Piston W/Magnet Slo | ot |
| 21 4 S'assy,Cage & Roller | 'S |
| 30 3 SHCS | |
| 31 1 Dowel Pin | |
| 32 2 Dowel Pin | |
| 40 2 Magnet | |

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation

- 1. Install sensors as shown.
- Adjust for desired end of stroke detection.









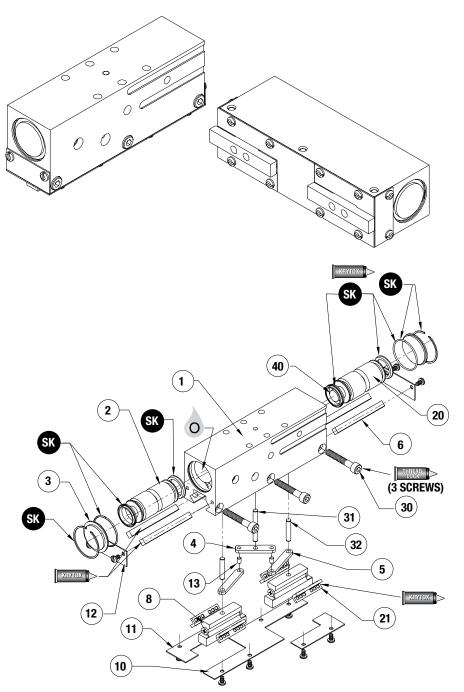






RPLC SERIES

Parallel Grippers | Maintenance and Assembly Procedure



| Item | Qty | Name |
|------|-----|------------------------|
| 01 | 1 | Body |
| 02 | 1 | Piston |
| 03 | 2 | Cap |
| 04 | 1 | Equalizer |
| 05 | 2 | Link |
| 06 | 4 | Way |
| 80 | 2 | Jaw |
| 10 | 1 | Cover, Bottom |
| 11 | 2 | Cover, Bottom, Corners |
| 12 | 2 | Cover, End |
| 13 | 2 | Bearing, Roller |
| 20 | 1 | Piston W/Magnet Slot |
| 21 | 4 | S'assy, Cage & Rollers |
| 30 | 3 | SHCS |
| 31 | 1 | Dowel Pin |
| 32 | 2 | Dowel Pin |
| 40 | 2 | Magnet |

Note: contact the robohand sales department for a complete spare parts list with order numbers and prices.

Assembly procedure

- 1) Lubricate and install seals.
- 2) Glue magnets into one piston, install pistons, caps and retaining rings.

- 3) Press dowel pin into center of body.
 4) Place links and equalizers into body.
 5) Press dowel pins into jaws.
 6) Place jaws through links and into pistons.
 7) Install cages on jaws.
- 8) Place ways behind cages with flat facing out and install screws.
- 9) Adjust preload.
- 10) Install bottom cover, bottom cover corners and end covers.

- **Preload adjustment procedure**1) Tighten center screw (#30) so that fingers preload adjustment procedure
- 2) Tighten outer screws in the same fashion. Bind slightly.
- 3) Cycle the gripper.
- 4) Re-adjust screws so that when you push the cage, the finger moves freely. (the finger movement should not feel gritty.)

Non-synchronous procedure

- 1) Remove end covers, bottom cover corners, and bottom cover.
- 2) Remove preload screws (#30) and ways.
- 3) Remove cages, jaws and dowel pins.
- 4) Remove equalizer, links, and roller bear-
- ings.
 5) Re-assemble jaws and dowel pins into pis-
- 6) Re-install cages on jaws.
- 7) Place ways behind cages with flat facing
- 8) Adjust preload. Install preload screws.
- Re-attach bottom cover, bottom cover corners and end covers. Gripper is now nonsynchronous.















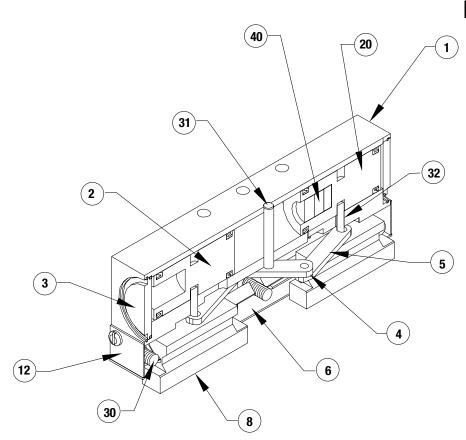






RPLC SERIES

Parallel Grippers | Maintenance and Assembly Procedure



| Item | Qty | Name |
|------|-----|------------------------|
| | | |
| 01 | 1 | Body |
| 02 | 1 | Piston |
| 03 | 2 | Cap |
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Note: contact the robohand sales department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions

2 23 24

Installation

- 1) Install sensors as shown.
- 2) Adjust for desired end of stroke detection.



















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